

Communications and Control Engineering



Bernard Brogliato

Nonsmooth Mechanics

Models, Dynamics and Control

Third Edition



Springer

Nonsmooth Mechanics Models Dynamics And Control Communications And Control Engineering

**Vincent Acary, Olivier
Bonneton, Bernard Brogliato**



Nonsmooth Mechanics Models Dynamics And Control Communications And Control Engineering:

Nonsmooth Mechanics Bernard Brogliato, 1999-03-30 Thank you for opening the second edition of this monograph which is devoted to the study of a class of nonsmooth dynamical systems of the general form $\dot{x} = f(x, u)$ where $x \in \mathbb{R}^n$ is the system's state vector $u \in \mathbb{R}^m$ is the vector of inputs and the function f represents a unilateral constraint that is imposed on the state. More precisely we shall restrict ourselves to a subclass of such systems namely mechanical systems subject to unilateral constraints on the position whose dynamical equations may be in a first instance written as $M\ddot{q} = g(q, u)$ where $q \in \mathbb{R}^n$ is the vector of generalized coordinates of the system and u is an input or controller that generally involves a state feedback loop $u = u(q, \dot{q}, z)$ with $\dot{z} = \dot{q}$ when the controller is a dynamic state feedback. Mechanical systems composed of rigid bodies interacting fall into this subclass. A general property of systems as in (0.1) and (0.2) is that their solutions are nonsmooth with respect to time. Nonsmoothness arises primarily from the occurrence of impacts or collisions or percussions in the dynamical behaviour when the trajectories attain the surface $f(x) = 0$. They are necessary to keep the trajectories within the subspace $f(x) \leq 0$ of the system's state space.

Nonsmooth Mechanics Bernard Brogliato, 2012-12-06 Thank you for opening the second edition of this monograph which is devoted to the study of a class of nonsmooth dynamical systems of the general form $\dot{x} = f(x, u)$ where $x \in \mathbb{R}^n$ is the system's state vector $u \in \mathbb{R}^m$ is the vector of inputs and the function f represents a unilateral constraint that is imposed on the state. More precisely we shall restrict ourselves to a subclass of such systems namely mechanical systems subject to unilateral constraints on the position whose dynamical equations may be in a first instance written as $M\ddot{q} = g(q, u)$ where $q \in \mathbb{R}^n$ is the vector of generalized coordinates of the system and u is an input or controller that generally involves a state feedback loop $u = u(q, \dot{q}, z)$ with $\dot{z} = \dot{q}$ when the controller is a dynamic state feedback. Mechanical systems composed of rigid bodies interacting fall into this subclass. A general property of systems as in (0.1) and (0.2) is that their solutions are nonsmooth with respect to time. Nonsmoothness arises primarily from the occurrence of impacts or collisions or percussions in the dynamical behaviour when the trajectories attain the surface $f(x) = 0$. They are necessary to keep the trajectories within the subspace $f(x) \leq 0$ of the system's state space.

Informatics in Control, Automation and Robotics Oleg Gusikhin, Kurosh Madani, 2019-04-18 The book focuses the latest endeavours relating researches and developments conducted in fields of Control Robotics and Automation. Through more than twenty revised and extended articles the present book aims to provide the most up to date state of art of the aforementioned fields allowing researcher PhD students and engineers not only updating their knowledge but also benefiting from the source of inspiration that represents the set of selected articles of the book. The deliberate intention of editors to cover as well theoretical facets of those fields as their practical accomplishments and implementations offers the benefit of gathering in a same volume a factual and well balanced prospect of nowadays research in those topics. A special attention toward Intelligent Robots and Control may characterize another benefit of this book.

Nonsmooth

Modeling and Simulation for Switched Circuits Vincent Acary, Olivier Bonnefon, Bernard Brogliato, 2010-10-19 Nonsmooth Modeling and Simulation for Switched Circuits concerns the modeling and the numerical simulation of switched circuits with the nonsmooth dynamical systems NSDS approach using piecewise linear and multivalued models of electronic devices like diodes transistors switches Numerous examples ranging from introductory academic circuits to various types of power converters are analyzed and many simulation results obtained with the INRIA open source SICONOS software package are presented Comparisons with SPICE and hybrid methods demonstrate the power of the NSDS approach Nonsmooth Modeling and Simulation for Switched Circuits is intended to researchers and engineers in the field of circuits simulation and design but may also attract applied mathematicians interested by the numerical analysis for nonsmooth dynamical systems as well as researchers from Systems and Control

Robotics and Automation Handbook Thomas R. Kurfess, 2018-10-03 As the capability and utility of robots has increased dramatically with new technology robotic systems can perform tasks that are physically dangerous for humans repetitive in nature or require increased accuracy precision and sterile conditions to radically minimize human error The Robotics and Automation Handbook addresses the major aspects of designing fabricating and enabling robotic systems and their various applications It presents kinetic and dynamic methods for analyzing robotic systems considering factors such as force and torque From these analyses the book develops several controls approaches including servo actuation hybrid control and trajectory planning Design aspects include determining specifications for a robot determining its configuration and utilizing sensors and actuators The featured applications focus on how the specific difficulties are overcome in the development of the robotic system With the ability to increase human safety and precision in applications ranging from handling hazardous materials and exploring extreme environments to manufacturing and medicine the uses for robots are growing steadily The Robotics and Automation Handbook provides a solid foundation for engineers and scientists interested in designing fabricating or utilizing robotic systems

Dynamics and Control of Advanced Structures and Machines Valerii P. Matveenko, Michael Krommer, Alexander K. Belyaev, Hans Irschik, 2019-03-08 The volume includes 30 contributions from the 3rd International Workshop on Advanced Dynamics and Model Based Control of Structures and Machines representing the frontiers in the mechanics of controlled machines and structures The Workshop held in Perm Russia in September 2017 continued a series of international workshops starting in with the Japan Austria Joint Workshop on Mechanics and Model Based Control of Smart Materials and Structures the Russia Austria Joint Workshop on Advanced Dynamics and Model Based Control of Structures and Machines and the first two editions of the International Workshop on Advanced Dynamics and Model Based Control of Structures and Machines The previous workshops took place in Linz Austria in September 2008 and April 2010 in St Petersburg Russia in July 2012 and in Vienna Austria in September 2015 The up to date contributions are authored by internationally re known leading experts in dynamics and control representing a broad spectrum of topics in the field of Advanced Structures and Machines both with respect to theoretical

aspects as well as applications to contemporary engineering problems *Adaptive Control of Nonsmooth Dynamic Systems*
Gang Tao, Frank L. Lewis, 2013-04-17 A complete reference to adaptive control of systems with nonsmooth industrial nonlinearities such as backlash dead zones component failure friction hysteresis saturation and time delays Actuator nonlinearities are ubiquitous in engineering practice and limit control system performance While standard feedback control alone cannot handle these nonsmooth nonlinearities effectively this book shows how such nonlinear characteristics can be compensated for by using adaptive and intelligent control techniques This allows desired system performance to be achieved in the presence of uncertain nonlinearities With surveys of literature and summaries of various design methods the contributors present new solutions to some important issues in adaptive control of systems with various sorts of nonsmooth nonlinearities The book motivates more research activities in the field of adaptive control of nonsmooth nonlinear industrial systems by formulating several challenging open problems in related areas *Robotic Systems for Handling and Assembly*
Daniel Schütz, Friedrich M. Wahl, 2010-11-20 Although parallel robots are known to offer many advantages with respect to accuracy dynamics and stiffness major breakthroughs in industrial applications have not yet taken place This is due to a knowledge gap preventing fast and precise execution of industrial handling and assembly tasks This book focuses on the design modeling and control of innovative parallel structures as well as the integration of novel machine elements Special attention is paid to the integration of active components into lightweight links and passive joints In addition new control concepts are introduced to minimize structural vibrations Although the optimization of robot systems itself allows a reduction of cycle times these can be further decreased by improved path planning robot programming and automated assembly planning concepts described by 25 contributions within this book The content of this volume is subdivided into four main parts dealing with Modeling and Design System Implementation Control and Programming as well as Adaptronics and Components This book is aimed at researchers and postgraduates working in the field of parallel robots as well as practicing engineers dealing with industrial robot development and robotic applications *Friction-Induced Vibration in Lead Screw Drives*
Orang Vahid-Araghi, Farid Golnaraghi, 2010-10-14 Friction Induced Vibration in Lead Screw Drives covers the dynamics of lead screw drives with an emphasis on the role of friction Friction induced vibration in lead screws can be the cause of unacceptably high levels of audible noise as well as loss of operation accuracy and shortened life Although lead screw drives have a long history and their mechanical design and manufacturing aspects are very well understood the role of friction in their dynamical behavior has not been comprehensively treated The book draws on the vast body of work on the subject of dynamical systems with friction such as disk brake systems and offers said treatment along with Unique coverage of modeling of multi DOF lead screw systems with friction Detailed analysis of negative damping mode coupling and kinematic constraint instability mechanisms in lead screws drives A practical parameter identification approach for the velocity dependent coefficient of friction in lead screw drives Friction Induced Vibration in Lead Screw Drives serves as the

definitive text on the friction induced vibration of lead screws and includes a practical case study where the developed methods are used to study the excessive noise problem of a lead screw drive system and to put forward design modifications that eliminate the friction induced vibrations

Analytical Mechanics: A Comprehensive Treatise On The Dynamics Of Constrained Systems (Reprint Edition) John G Papastavridis, 2014-03-06 This is a comprehensive state of the art treatise on the energetic mechanics of Lagrange and Hamilton that is classical analytical dynamics and its principal applications to constrained systems contact rolling and servoconstraints It is a book on advanced dynamics from a unified viewpoint namely the kinetic principle of virtual work or principle of Lagrange As such it continues renovates and expands the grand tradition laid by such mechanics masters as Appell Maggi Whittaker Heun Hamel Chetaev Synge Pars Lur Gantmacher Neimark and Fufaev Many completely solved examples complement the theory along with many problems all of the latter with their answers and many of them with hints Although written at an advanced level the topics covered in this 1400 page volume the most extensive ever written on analytical mechanics are eminently readable and inclusive It is of interest to engineers physicists and mathematicians advanced undergraduate and graduate students and teachers researchers and professionals all will find this encyclopedic work an extraordinary asset for classroom use or self study In this edition corrections of the original edition 2002 have been incorporated

Nonsmooth Lyapunov Analysis in Finite and Infinite Dimensions Yury Orlov, 2020-02-08 Nonsmooth Lyapunov Analysis in Finite and Infinite Dimensions provides helpful tools for the treatment of a broad class of dynamical systems that are governed not only by ordinary differential equations but also by partial and functional differential equations Existing Lyapunov constructions are extended to discontinuous systems those with variable structure and impact by the involvement of nonsmooth Lyapunov functions The general theoretical presentation is illustrated by control related applications the nonsmooth Lyapunov construction is particularly applied to the tuning of sliding mode controllers in the presence of mismatched disturbances and to orbital stabilization of the bipedal gait The nonsmooth construction is readily extendible to the control and identification of distributed parameter and time delay systems The first part of the book outlines the relevant fundamentals of benchmark models and mathematical basics The second concentrates on the construction of nonsmooth Lyapunov functions Part III covers design and applications material This book will benefit the academic research and graduate student interested in the mathematics of Lyapunov equations and variable structure control stability analysis and robust feedback design for discontinuous systems It will also serve the practitioner working with applications of such systems The reader should have some knowledge of dynamical systems theory but no background in discontinuous systems is required they are thoroughly introduced in both finite and infinite dimensional settings

Deutsche Nationalbibliographie und Bibliographie der im Ausland erschienenen deutschsprachigen Veröffentlichungen, 1996

Nonsmooth Mechanics of Solids Jaroslav Haslinger, Georgios E. Stavroulakis, 2007-08-03 Mechanics have played an important role in mathematics from infinitesimal calculus calculus of

variations partial differential equations and numerical methods finite elements Originally mechanics treated smooth objects Technological progress has evoked the necessity to model and solve more complicated problems like unilateral contact and friction plasticity delamination and adhesion advanced materials etc The new tools include convex analysis differential calculus for convex functions and subgradients of convex functions and extensions for nonconvex problems Nonsmooth mechanics is a relatively complex field and requires a good knowledge of mechanics and a good background in some parts of modern mathematics The present volume of lecture notes follows a very successful advanced school with the aim to cover as much as possible all these aspects Therefore the contributions cover mechanical aspects as well as the mathematical and numerical treatment

Dissipative Systems Analysis and Control Bernard Brogliato, Rogelio Lozano, Bernhard Maschke, Olav Egeland, 2019-07-03 The third edition of the now standard Dissipative Systems Analysis and Control presents a revised and expanded treatment of dissipative systems theory constituting a self contained advanced introduction for graduate students researchers and practising engineers It examines linear nonlinear and nonsmooth systems with many examples in each chapter occasional infinite dimensional examples are also included Throughout emphasis is placed on the use of the dissipative properties of a system for the design of stable and robust feedback control laws or state observers The theory is substantiated by experimental results and by reference to its application in illustrative physical cases Lagrangian systems passivity based and adaptive controllers are covered thoroughly The third edition is substantially updated to accommodate new material within the existing chapter structure The additions include the introduction of negative imaginary transfer functions the design of stable state observers that use passivity as a tool for their stability analysis a new section on robust set valued control of uncertain Lagrangian systems extended section on discrete time systems especially the preservation of dissipativity after discretization a thorough treatment of nonsmooth set valued Lur e systems well posedness and stability an extended chapter on the Kalman Yakubovich Popov Lemma and over 1000 references

Surveys in

Differential-Algebraic Equations I Achim Ilchmann, Timo Reis, 2013-03-19 The need for a rigorous mathematical theory for Differential Algebraic Equations DAEs has its roots in the widespread applications of controlled dynamical systems especially in mechanical and electrical engineering Due to the strong relation to ordinary differential equations the literature for DAEs mainly started out from introductory textbooks As such the present monograph is new in the sense that it comprises survey articles on various fields of DAEs providing reviews presentations of the current state of research and new concepts in Controllability for linear DAEs Port Hamiltonian differential algebraic systems Robustness of DAEs Solution concepts for DAEs DAEs in circuit modeling The results in the individual chapters are presented in an accessible style making this book suitable not only for active researchers but also for graduate students with a good knowledge of the basic principles of DAEs for self study

Fundamentals of Multibody Dynamics Farid Amirouche, 2007-05-24 Because of its versatility in analyzing a broad range of applications multibody dynamics has grown in the past two decades to be an important tool for

designing prototyping and simulating complex articulated mechanical systems This textbook brings together diverse concepts and bridges the gap between dynamics and engineering applications such as microrobotics virtual reality simulation of interactive mechanical systems nanomechanics flexible biosystems crash simulation and biomechanics The book puts into perspective the importance of modeling in the dynamic simulation and problem solving in the above mentioned fields Facilitating the understanding of rigid body dynamics the author presents a compiled overview of particle dynamics and Newton's second law of motion A particular strength of the book is its use of matrices to generate kinematic coefficients that help formulate the governing equations of motion

Proceedings, 2005

Nonsmooth Impact Mechanics Bernard Brogliato, 2014-03-12 The field of nonsmooth impact dynamics and its applications to the control of robotic systems is examined in this monograph The mathematical foundations of the dynamics of systems of rigid bodies submitted to a set of unilateral constraints are introduced Following on from this the macroscopic physical laws of shocks restitution roles are described and commented on In view of the applications to feedback control stability properties of trajectories of various types of measure differential equations are reviewed This includes a general stability analysis framework suitable for a class of impacting robotic systems performing complete tasks Finally feedback control of manipulators subject to unilateral constraints which consist of a class of hybrid systems is studied

Dynamical Contact Problems with Friction Walter Sestro, 2007-03-06 Friction contacts are used to transmit forces or to dissipate energy The aim of this second edition is to describe an efficient procedure to model dynamical contact problems with friction This procedure is applied to different practical problems and validated by experiments A thorough understanding of friction phenomena can lead to improvements like the reduction of noise and maintenance costs increased useful life of machines and improved energy efficiency

Numerical Methods for Nonsmooth Dynamical Systems Vincent Acary, Bernard Brogliato, 2008-01-30 This book concerns the numerical simulation of dynamical systems whose trajectories may not be differentiable everywhere They are named nonsmooth dynamical systems They make an important class of systems first because of the many applications in which nonsmooth models are useful secondly because they give rise to new problems in various fields of science Usually nonsmooth dynamical systems are represented as differential inclusions complementarity systems evolution variational inequalities each of these classes itself being split into several subclasses The book is divided into four parts the first three parts being sketched in Fig 0 1 The aim of the first part is to present the main tools from mechanics and applied mathematics which are necessary to understand how nonsmooth dynamical systems may be numerically simulated in a reliable way Many examples illustrate the theoretical results and an emphasis is put on mechanical systems as well as on electrical circuits the so called Filippov's systems are also examined in some detail due to their importance in control applications The second and third parts are dedicated to a detailed presentation of the numerical schemes A fourth part is devoted to the presentation of the software platform Siconos This book is not a textbook on numerical analysis of nonsmooth systems in the sense that despite the main

results of numerical analysis convergence order of consistency etc being presented their proofs are not provided

This book delves into Nonsmooth Mechanics Models Dynamics And Control Communications And Control Engineering. Nonsmooth Mechanics Models Dynamics And Control Communications And Control Engineering is a crucial topic that needs to be grasped by everyone, from students and scholars to the general public. This book will furnish comprehensive and in-depth insights into Nonsmooth Mechanics Models Dynamics And Control Communications And Control Engineering, encompassing both the fundamentals and more intricate discussions.

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